A model reduction approach for inverse problems with operator valued data

Matthias Schlottbom<br>joint work with Jürgen Dölz (U Bonn), Herbert Egger (TU Darmstadt/Linz)

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## Outline

Fluorescence diffuse optical tomography
Model
Inverse problem
Outline of model reduction approach

Abstract Analysis: Model reduction for $\mathcal{T} c=\mathcal{V}^{\prime} \mathcal{D}(c) \mathcal{U}$
Properties of the forward operator
Step 1: Tensor product approximation
Step 2: Quasi-optimal compression

Model reduction in action: Application to FDOT
Truth approximation and implementation
Complexity estimates
Runtimes and ranks

Conclusion

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## Fluorescence optical tomography: forward problem: $c \mapsto M$


concentration
[Arridge, Schotland: Optical tomography: forward and inverse problems, Inverse Problems, 25 (2009)]
[Egger et al: On forward and inverse models in fluorescence diffuse optical tomography, IPI, 4 (2010)]

## Fluorescence optical tomography: forward problem: $c \mapsto M$


concentration

excitation

## Excitation field generated by source $q_{j}$

$$
\begin{aligned}
-\nabla \cdot\left(\kappa_{x} \nabla u_{x, j}\right)+\mu_{x} u_{x, j} & =0 & \text { in } \Omega \\
\kappa_{x} \partial_{n} u_{x, j}+\rho_{x} u_{x, j} & =q_{j} & \text { on } \partial \Omega
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$$

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$$

Emission field for fluorophore concentration $c$ and excitation field $u_{x, j}$

$$
\begin{aligned}
-\nabla \cdot\left(\kappa_{m} \nabla u_{m, j}\right)+\mu_{m} u_{m, j} & =c u_{x, j} & & \text { in } \Omega \\
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\end{aligned}
$$

Measurements at detector (pixel) $d_{i}: M_{i j}=\int_{\partial \Omega} d_{i}(x) u_{m, j}(x) d \sigma(x)$
[Arridge, Schotland: Optical tomography: forward and inverse problems, Inverse Problems, 25 (2009)]
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## Inverse Problem

- $\mathrm{M} \approx \mathcal{M}=\mathcal{M}(c): q \rightarrow u_{m \mid \partial \Omega}$ (infinite dim.) measurement operator
- Use of $\mathcal{M}$ yields algorithms that are independent of the discretization

concentration $c$


$$
\text { solve } \mathcal{T} c=\mathcal{M}^{\delta}
$$


measurements: $\mathcal{M}$

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concentration $c$
Tikhonov regularization
Regularized normal equations


$$
\text { solve } \mathcal{T} c=\mathcal{M}^{\delta}
$$


measurements: $\mathcal{M}$

$$
\left\|\mathcal{T} c-\mathcal{M}^{\delta}\right\|^{2}+\alpha\|c\|^{2} \rightarrow \min
$$

$$
\left(\mathcal{T}^{\star} \mathcal{T}+\alpha \mathcal{I}\right) c_{\alpha}^{\delta}=\mathcal{T}^{\star} \mathcal{M}^{\delta}
$$

- solve with conjugate gradients (apply $\mathcal{T} c$ and $\mathcal{T}^{\star} M$ (its truth approximation))
- expensive for large parameter space and many measurements
[Freiberger et al: High-performance image reconstruction in fluorescence tomography on desktop computers and graphics hardware, Biomed. Opt. Express, 2 (2011)]


## Pathway to model reduction via projections

## Projection

$$
\mathcal{T}_{N}=\mathcal{Q}_{N} \mathcal{T}
$$

Error bound

$$
\left\|\mathcal{Q}_{N} \mathcal{T}-\mathcal{T}\right\| \leq \delta
$$

Reconstruction

$$
\left(\mathcal{T}_{N}^{\star} \mathcal{T}_{N}+\alpha \mathcal{I}_{N}\right) c_{\alpha, N}^{\delta}=\mathcal{T}_{N}^{\star} \mathcal{M}_{N}^{\delta}
$$

## Reconstruction error bound

$$
\left\|c_{\alpha, N}^{\delta}-c_{\alpha}^{\delta}\right\| \leq C(\alpha) \delta
$$

[Bakushinsky, Kokurin: Iterative Methods for Approximate Solution of Inverse Problems. Springer 2004]
[Neubauer: An a posteriori parameter choice for Tikhonov regularization in the presence of modeling errors. APNUM 4 (1988)]

## Offline-Online decomposition

Offline. Setup of the approximations $\mathcal{Q}_{N}, \mathcal{T}_{N}^{\star}$, and $\mathcal{T}_{N} \mathcal{T}_{N}^{\star}$.
Online. Computation of the regularized solution requires

| step | computations | complexity | memory |
| :--- | :--- | :--- | :--- |
| compression | $\mathcal{M}_{N}^{\delta}=\mathcal{Q}_{N} \mathcal{M}^{\delta}$ | $N k^{2}$ | $N k^{2}$ |
| analysis | $z_{\alpha, N}^{\delta}=g_{\alpha}\left(\mathcal{T}_{N} \mathcal{T}_{N}^{\star}\right) \mathcal{M}_{N}^{\delta}$ | $N^{2}$ | $N^{2}$ |
| synthesis | $C_{\alpha, N}^{\delta}=\mathcal{T}_{N}^{\star} z_{\alpha, N}^{\delta}$ | $N m$ | $N m$ |

Truth approximation $\mathcal{T} \in \mathbb{R}^{m \times k^{2}}$

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Truth approximation $\mathcal{T} \in \mathbb{R}^{m \times k^{2}}$
$\mathcal{T}_{N}$ being a truncated SVD of $\mathcal{T}$ is the benchmark, but expensive!
see, e.g., [Hochstenbach 2001, Markel et al 2003, Stoll 2012, Chaillat et al 2012, Musco et al 2015,...]

## A decomposition of the forward operator: $\mathcal{T}=\mathcal{V}^{\prime} \mathcal{D}(\cdot) \mathcal{U}$

## Adjoint emission problem

$$
\begin{aligned}
-\nabla \cdot\left(\kappa_{m} \nabla v_{m}\right)+\mu_{m} v_{m} & =0 \quad
\end{aligned} \quad \text { in } \quad \Omega,
$$

Solution operators of excitation and adjoint emission problem

$$
\begin{aligned}
& \mathcal{U}: q_{x} \mapsto \mathcal{U} q_{x}:=u_{x} \\
& \mathcal{V}: q_{m} \mapsto \mathcal{V} q_{m}:=v_{m} .
\end{aligned}
$$

## Multiplication operator

$$
\mathcal{D}(c) u=c u, \quad \text { i.e. } \quad\langle\mathcal{D}(c) u, v\rangle=\int_{\Omega} c u v d x
$$

One can show that $u_{m \mid \partial \Omega}=\mathcal{V}^{\prime} \mathcal{D}(c) u_{x}$ in correct functional analytic setting, i.e.,

$$
\mathcal{T} c=\mathcal{V}^{\prime} \mathcal{D}(c) \mathcal{U}
$$

[Egger et al: On forward and inverse models in fluorescence diffuse optical tomography, IPI, 4 (2010)]

## Procedure for setting up the projection for $\mathcal{T}=\mathcal{V}^{\prime} \mathcal{D}(\cdot) \mathcal{U}$

## 1. Accurate projections

$$
\mathcal{U}_{K}=\mathcal{U} \mathcal{Q}_{K, \mathcal{U}} \quad \text { and } \quad \mathcal{V}_{K}=\mathcal{V} \mathcal{Q}_{K, \mathcal{V}}
$$

lead to

$$
\mathcal{T}_{K, K} c=\mathcal{Q}_{K, K} \mathcal{T} c=\mathcal{V}_{K}^{\prime} \mathcal{D}(c) \mathcal{U}_{K}, \quad \mathcal{M}_{K, K}^{\delta}=\left(\mathcal{Q}_{K, \mathcal{V}}^{\prime} \mathcal{M}^{\delta}\right) \mathcal{Q}_{K, \mathcal{U}}
$$

with error bound $\left\|\mathcal{T}_{K, K}-\mathcal{T}\right\| \leq \delta$
2. Further compression of $\mathcal{T}_{K, K}$ gives rise to desired projection

$$
\mathcal{Q}_{N}=\mathcal{P}_{N} \mathcal{Q}_{K, K}, \quad \mathcal{M}_{N}^{\delta}=\mathcal{P}_{N} \mathcal{M}_{K, K}^{\delta}
$$

Remark. Computation of $\mathcal{M}_{K, K}^{\delta}=\left(\mathcal{Q}_{K, \mathcal{V}}^{\prime} \mathcal{M}^{\delta}\right) \mathcal{Q}_{K, \mathcal{U}}$ requires only $O\left(K k+K^{2}\right)$ mem instead of $O\left(N k^{2}\right)$ if tensor structure is used.

Related to step 1.: [Herrmann et al 2009, Krebs et al 2009, Roosta-Khorasani et al 2014, Markel et al 2019]

## Model reduction in action: Application to FDOT <br> Truth approximation and implementation <br> Complexity estimates <br> Runtimes and ranks

Conclusion

## Abstract setting

Assumptions. $\mathbb{U}, \mathbb{V}, \mathbb{X}, \mathbb{Y}, \mathbb{Z}$ separable Hilbert spaces

$$
\mathcal{U} \in \mathbb{H} \mathbb{S}(\mathbb{Y}, \mathbb{U}), \quad \mathcal{V} \in \mathbb{H} \mathbb{S}(\mathbb{Z}, \mathbb{V}), \quad \mathcal{D} \in \mathcal{L}\left(\mathbb{X}, \mathcal{L}\left(\mathbb{U}, \mathbb{V}^{\prime}\right)\right)
$$

recall: Any $\mathcal{S} \in \mathcal{L}(\mathbb{A}, \mathbb{B})$ compact has singular value decomposition (SVD)

$$
\mathcal{S} a=\sum_{k=1}^{\infty}\left(a, a_{k}\right)_{\mathbb{A}} \sigma_{k, \mathcal{S}} b_{k}
$$

with ONBs $\left\{a_{k}\right\} \subset \mathbb{A}$ and $\left\{b_{k}\right\} \subset \mathbb{B}$. Truncated SVD

$$
\mathcal{S}_{K} a=\sum_{k=1}^{K}\left(a, a_{k}\right)_{\mathbb{A}} \sigma_{k, \mathcal{S}} b_{k}
$$

Error $\left\|\mathcal{S}-\mathcal{S}_{K}\right\|_{\mathcal{L}(\mathbb{A}, \mathbb{B})}=\sigma_{K+1, \mathcal{S}}$,
$\mathcal{S} \in \mathbb{H} \mathbb{S}(\mathbb{A}, \mathbb{B})$ iff $\left\{\sigma_{k, \mathcal{S}}\right\}_{k} \in \ell_{2}$, and $\|\mathcal{S}\|_{\mathbb{H} \mathbb{S}(\mathbb{A}, \mathbb{B})}^{2}=\sum_{k=1}^{\infty} \sigma_{k, \mathcal{S}}^{2}$
see, e.g., [Hackbusch: Tensor spaces and numerical tensor calculus. Springer. 2014]

## Properties of the forward operator

$\mathbb{U}, \mathbb{V}, \mathbb{X}, \mathbb{Y}, \mathbb{Z}$ separable Hilbert spaces

$$
\mathcal{U} \in \mathbb{H} \mathbb{S}(\mathbb{Y}, \mathbb{U}), \quad \mathcal{V} \in \mathbb{H} \mathbb{S}(\mathbb{Z}, \mathbb{V}), \quad \mathcal{D} \in \mathcal{L}\left(\mathbb{X}, \mathcal{L}\left(\mathbb{U}, \mathbb{V}^{\prime}\right)\right)
$$

Lemma. $\mathcal{T}(c)=\mathcal{V}^{\prime} \mathcal{D}(c) \mathcal{U}$ defines a bounded linear compact operator $\mathcal{T}: \mathbb{X} \rightarrow \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)$.

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## Proof (sketch).

- Consider TSVDs: $\mathcal{U}_{K}=\mathcal{U} \mathcal{Q}_{\kappa, \mathcal{U}}$ and $\mathcal{V}_{K}=\mathcal{V} \mathcal{Q}_{K, \mathcal{V}}$ with rank $K$ such that

$$
\left\|\mathcal{U}-\mathcal{U}_{K}\right\|_{\mathcal{L}(\mathbb{Y}, \mathbb{U})} \lesssim K^{-1 / 2} \quad \text { and } \quad\left\|\mathcal{V}-\mathcal{V}_{K}\right\|_{\mathcal{L}(\mathbb{Z}, \mathbb{V})} \lesssim K^{-1 / 2}
$$

- Define $\mathcal{T}_{K, K}: \mathbb{X} \rightarrow \mathbb{H} \mathbb{S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)$ by $\mathcal{T}_{K, K} c=\mathcal{V}_{K}^{\prime} \mathcal{D}(c) \mathcal{U}_{K}$
- $\operatorname{rank} \mathcal{T}_{K, K} \leq K^{2}$.
- Show $\left\|\mathcal{T}-\mathcal{T}_{K, K}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)} \lesssim K^{-1 / 2}$ via triangle inequality.


## Step 1: Tensor product approximation of $\mathcal{T}$

Corollary. For any $\delta>0$ there exists $K \in \mathbb{N}$ with $K \lesssim \delta^{-2}$ such that

$$
\left\|\mathcal{U}-\mathcal{U}_{K}\right\|_{\mathcal{L}(\mathbb{Y}, \mathbb{U})} \leq \delta \quad \text { and } \quad\left\|\mathcal{V}-\mathcal{V}_{K}\right\|_{\mathcal{L}(\mathbb{Z}, \mathbb{V})} \leq \delta
$$

and $\mathcal{T}_{K, K} c=\mathcal{V}_{K}^{\prime} \mathcal{D}(c) \mathcal{U}_{K}$ satisfies

$$
\left\|\mathcal{T}-\mathcal{T}_{K, K}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)} \lesssim \delta
$$

If $\sigma_{k, \mathcal{U}}, \sigma_{k, \mathcal{V}} \lesssim k^{-\alpha}$ for $\alpha>1 / 2$, then $K \simeq \delta^{-1 / \alpha}$ and $\operatorname{rank}\left(T_{K, K}\right) \lesssim \delta^{-2 / \alpha}$.

[^0]
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Can we do better?

Compare to: [Markel et al: Fast linear inversion for highly overdetermined inverse scattering problems, Inverse Problems, 35 (2019)]

## Step 1': Hyperbolic cross approximation of $\mathcal{T}$

Lemma. Let $\sigma_{k, \mathcal{U}} \lesssim k^{-\beta}$ and $\sigma_{k, \mathcal{V}} \lesssim k^{-\alpha}$ for $\beta>1 / 2$ and $\alpha>\beta+1 / 2$. Then for any $\delta>0$, we can construct $\mathcal{T}_{\widehat{\kappa}}$ with rank $\lesssim \delta^{-1 / \beta}$ :

$$
\left\|\mathcal{T}-\mathcal{T}_{\widehat{K}}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)} \lesssim \delta .
$$

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$$

## Remarks.

(i) $\operatorname{rank} \mathcal{T}_{K, K}=K^{2} \simeq \delta^{-2 / \alpha}$, with $\mathcal{T}_{K, K} c=\mathcal{V}_{K}^{\prime} \mathcal{D}(c) \mathcal{U}_{K}$
(ii) $\operatorname{rank} \mathcal{T}_{\widehat{K}} \lesssim \delta^{-1 /(\alpha-(1 / 2+\epsilon))} \Longrightarrow \operatorname{rank} \mathcal{T}_{K, K}$ is not optimal if $\alpha>1$
(iii) $\mathcal{T}_{\widehat{K}}$ can be realized as a hyperbolic cross approximation of $\mathcal{T}_{K, K}$.

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Proof (sketch). Let $\left\{\sigma_{k, *}, a_{k, *}, b_{k, *}\right\}$ denote the singular systems for $\mathcal{U}$ and $\mathcal{V}^{\prime}$, respectively. The hyperbolic cross approximation

$$
\mathcal{T}_{\widehat{\kappa}}(c)=\sum_{k \geq 1} \sum_{\ell=1}^{L_{k}} \sigma_{\ell, \mathcal{U}} \sigma_{k, \mathcal{V}^{\prime}}\left(\cdot, a_{\ell, \mathcal{U}}\right)_{\mathbb{Y}}\left\langle\mathcal{D}(c) b_{\ell, \mathcal{U}}, a_{k}, \mathcal{V}^{\prime}\right\rangle_{\mathbb{V}^{\prime} \times \mathbb{V}} b_{k, \mathcal{V}^{\prime}}
$$

with the choice $L_{k}=\left\lfloor\widehat{K} / k^{1+\epsilon}\right\rfloor, \widehat{K} \simeq \delta^{-1 / \beta}$, and $\epsilon=(\alpha-\beta-1 / 2) /(2 \beta)>0$ has the required properties.

[^1]
## Step 2: Quasi-optimal low-rank approximation via TSVD

Lemma. Let $\delta>0$ and let $\mathcal{T}^{\delta}: \mathbb{X} \rightarrow \mathbb{H} \mathbb{S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)$ be a linear compact operator such that $\left\|\mathcal{T}^{\delta}-\mathcal{T}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)} \leq C \delta$ for some $C>0$. Let $\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}$ denote the truncated singular value decomposition of $\mathcal{T}^{\delta}$ with minimal rank $N^{\delta}$ such that

$$
\left\|\mathcal{T}^{\delta}-\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)} \leq(C+1) \delta
$$

Then $N^{\delta} \leq N^{\text {svd }}$, the rank of the TSVD of $\mathcal{T}$ that yields a $\delta$ error, and

$$
\left\|\mathcal{T}-\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)} \leq(2 C+1) \delta
$$

i.e., $\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}$ is a $\delta$-approximation for $\mathcal{T}$ with quasi-optimal rank.

## Proof: Step 1. Perturbation of singular values

Claim. (cf [Kato1966]): Let $\left\|\mathcal{T}^{\delta}-\mathcal{T}\right\| \leq C \delta$. For each $k \in \mathbb{N}$ one has

$$
\sigma_{k}-C \delta \leq \sigma_{k}^{\delta} \leq \sigma_{k}+C \delta
$$

where $\left\{\sigma_{k}\right\}$ and $\left\{\sigma_{k}^{\delta}\right\}$ denote the singular values of $\mathcal{T}$ and $\mathcal{T}^{\delta}$, respectively.
Choose $\varepsilon>0$, and let $\mathcal{P}_{M}^{\text {svd }} \mathcal{T}$ denote the TSVD of $\mathcal{T}$ with optimal rank $M$ s.t.

$$
\left\|\mathcal{P}_{M}^{\text {svd }} \mathcal{T}-\mathcal{T}\right\| \leq \varepsilon .
$$

Optimality of $M$ and the non-expansiveness of the projection implies

$$
\begin{aligned}
\sigma_{M+1}^{\delta}=\left\|\left(\mathcal{I}-\mathcal{P}_{M}^{\delta}\right) \mathcal{T}^{\delta}\right\| & \leq\left\|\left(\mathcal{I}-\mathcal{P}_{M}^{\text {svd }}\right) \mathcal{T}^{\delta}\right\| \\
& \leq\left\|\left(\mathcal{I}-\mathcal{P}_{M}^{\text {svd }}\right) \mathcal{T}\right\|+\left\|\left(\mathcal{I}-\mathcal{P}_{M}^{\text {svd }}\right)\left(\mathcal{T}-\mathcal{T}^{\delta}\right)\right\| \leq \varepsilon+C \delta .
\end{aligned}
$$

For $\varepsilon=\sigma_{k+1}$, we have $M=M(\varepsilon)=k$, and we conclude that

$$
\sigma_{k+1}^{\delta} \leq \sigma_{k+1}+C \delta
$$

The second inequality follows by interchanging the roles of $\mathcal{T}$ and $\mathcal{T}^{\delta}$.

## Proof: Step 2.

Let $N^{\delta}$ be as in the lemma: $\sigma_{N^{\delta}+1}^{\delta} \leq(C+1) \delta<\sigma_{N^{\delta}}^{\delta}$.
Let $N^{\text {svd }}=M(\delta)$ as defined in Step 1: $\sigma_{N^{\text {svd }}+1} \leq \delta$.
The claim implies

$$
\sigma_{N^{\text {svd }}+1}^{\delta} \leq \sigma_{N^{\text {svd }}+1}+C \delta \leq(C+1) \delta
$$

Monotonicity of the singular values: $N^{\delta} \leq N^{\text {svd }}$.
Finally,

$$
\left\|\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}-\mathcal{T}\right\| \leq\left\|\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}-\mathcal{T}^{\delta}\right\|+\left\|\mathcal{T}^{\delta}-\mathcal{T}\right\| \leq(2 C+1) \delta
$$

i.e., $\mathcal{P}_{N^{\delta}}^{\delta} \mathcal{T}^{\delta}$ is a $\delta$-approximation for $\mathcal{T}$ with quasi-optimal rank $N^{\delta} \leq N^{\text {svd }}$.

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## Function space setting

recall: Assumptions of abstract theory: $\mathbb{U}, \mathbb{V}, \mathbb{X}, \mathbb{Y}, \mathbb{Z}$ separable Hilbert spaces,

$$
\mathcal{U} \in \mathbb{H} \mathbb{S}(\mathbb{Y}, \mathbb{U}), \quad \mathcal{V} \in \mathbb{H} \mathbb{S}(\mathbb{Z}, \mathbb{V}), \quad \mathcal{D} \in \mathcal{L}\left(\mathbb{X}, \mathcal{L}\left(\mathbb{U}, \mathbb{V}^{\prime}\right)\right)
$$

Solution operators

$$
\begin{array}{ll}
\mathcal{U}: H^{1}(\partial \Omega) \rightarrow H^{1}(\Omega), & q_{x} \mapsto \mathcal{U} q_{x}:=u_{x} \\
\mathcal{V}: H^{1}(\partial \Omega) \rightarrow H^{1}(\Omega), & q_{m} \mapsto \mathcal{V} q_{m}:=v_{m}
\end{array}
$$

Multiplication operator

$$
\mathcal{D}: L^{2}(\Omega) \rightarrow \mathcal{L}\left(H^{1}(\Omega), H^{1}(\Omega)^{\prime}\right), \quad \mathcal{D}(c) u=c u
$$

Function spaces

$$
\mathbb{U}=\mathbb{V}=H^{1}(\Omega), \mathbb{Y}=\mathbb{Z}=H^{1}(\partial \Omega), \mathbb{X}=L^{2}(\Omega)
$$

Lemma. The operators $\mathcal{U}$ and $\mathcal{V}$ are Hilbert-Schmidt and their singular values decay like $\sigma_{k, \mathcal{U}} \lesssim k^{-3 /(2 d-2)}$ and $\sigma_{k, \mathcal{V}} \lesssim k^{-3 /(2 d-2)}$.

## Truth approximation via standard FEM

- $T_{h}$ a quasi-uniform conforming triangulation of the domain $\Omega$
- $\mathbb{P}_{1}$-Lagrange finite elements: $\mathbb{U}_{h}, \mathbb{V}_{h} \subset H^{1}(\Omega), \mathbb{X}_{h} \subset \mathbb{X} ; \operatorname{dim}=m \approx h^{-d}$
- induced boundary finite elements: $\mathbb{Y}_{h}, \mathbb{Z}_{h} \subset H^{1}(\partial \Omega) ; \operatorname{dim}=k \approx h^{-d+1}$
$\mathrm{U} \in \mathbb{R}^{m \times k}$ discrete counterpart of the operator $\mathcal{U}$ :

$$
\left(K_{x}+M_{x}+R_{x}\right) U=E_{x} Q_{x}
$$

$\mathrm{V} \in \mathbb{R}^{m \times k}$ discrete counterpart of the operator $\mathcal{V}$ :

$$
\left(K_{m}+M_{m}+R_{m}\right) V=E_{m} Q_{m} .
$$

Algebraic form of the truth approximation

$$
\mathrm{T}(\mathrm{c})=\mathrm{V}^{\top} \mathrm{D}(\mathrm{c}) \mathrm{U}
$$

Discrete measurement

$$
\mathrm{M}_{i j}=\left(\mathrm{V}^{\top} \mathrm{D}(\mathrm{c}) \mathrm{U}\right)_{i j}=\mathrm{V}(:, i)^{\top} \mathrm{D}(\mathrm{c}) \mathrm{U}(:, j)
$$

## Numerical example: setup



Computational domain and coarse mesh



Dimensions: $m=\operatorname{dim}\left(\mathbb{X}_{h}\right)=\operatorname{dim}\left(\mathbb{U}_{h}\right)=\operatorname{dim}\left(\mathbb{V}_{h}\right)$ and $k=\operatorname{dim}\left(\mathbb{Y}_{h}\right)=\operatorname{dim}\left(\mathbb{Z}_{h}\right)$ discretization error: $d e_{h}=\left\|\mathcal{T}_{h}-\mathcal{T}\right\|_{\mathcal{L}\left(\mathbb{X}, \mathbb{H S}\left(\mathbb{Y}, \mathbb{Z}^{\prime}\right)\right)}$

| ref | 0 | 1 | 2 | 3 | 4 | 5 |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $m$ | 993 | 3881 | 15345 | 61025 | 243393 | 927161 |
| $k$ | 88 | 176 | 352 | 704 | 1408 | 2816 |
| $d e_{h}$ | $6.31 \cdot 10^{-4}$ | $1.69 \cdot 10^{-4}$ | $4.34 \cdot 10^{-5}$ | $1.10 \cdot 10^{-5}$ | $2.75 \cdot 10^{-6}$ | - |

Remark. For ref $=5, \mathrm{~T}: \mathbb{R}^{927161} \rightarrow \mathbb{R}^{2816 \times 2816}$; storage 56TB of memory; one single evaluation of $\mathrm{T}(\mathrm{c})$ require approximately 7 T flops.

## Memory and operation cost

## Offline

- Compression of $\mathrm{U}, \mathrm{V} \in \mathbb{R}^{m \times k}$ : mem $O(k m)$, ops $O\left(k^{2} m+k^{3}\right)$ These steps are at most as expensive as one application of T .
- Compression: mem $O(\mathrm{Km})$
- tensor product TKK: ops $O\left(\mathrm{~K}^{2} m\right)$
- hyperbolic cross TK: ops $O(m \mathrm{~K} \ln \mathrm{~K})$
- Recompression to obtain TN with quasi-optimal rank N
- of tensor product: ops $O\left(m K^{4}+K^{6}\right)$
- of hyperbolic cross: ops $O\left(m(\mathrm{~K} \ln \mathrm{~K})^{2}+(\mathrm{K} \ln \mathrm{K})^{4}\right)$

Use hyperbolic cross approximation TK to compute TN.
Online (inverse problem)

- Data compression: mem $O(\mathrm{~K} k)$, ops $O\left(\mathrm{~K}^{2} k+\mathrm{K} k^{2}\right)$
- Analysis: depends on N only (cheap!)
- Synthesis: mem $O(m \mathrm{~N})$, ops $O(m \mathrm{~N})$


## Truncation ranks N and timings for SVD

of T (full operator), TKK (tensor product approx.) and TK (hyperbolic cross approx.)

| refinements | 0 | 1 | 2 | 3 | 4 | 5 |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- |
| svd(T) in sec | 6.46 | 28.23 | 284.33 | - | - | - |
| N(T) | 231 | 303 | 473 | - | - | - |
| svd(TKK) in sec | 6.45 | 15.05 | 48.40 | 248.42 | 994.66 | - |
| N(TKK) | 231 | 276 | 296 | 310 | 314 | - |
| setup of TK, TKTKt in sec | 0.01 | 0.013 | 1.38 | 6.31 | 30.48 | 140.32 |
| rank(TK) | 403 | 933 | 1725 | 1867 | 1905 | 1917 |
| svd(TK) in sec | 0.08 | 0.87 | 2.57 | 3.51 | 3.87 | 4.03 |
| N(TK) | 166 | 266 | 391 | 396 | 401 | 403 |

## Timings and error $\left\|c_{\alpha}^{\delta}-c^{\dagger}\right\|$ for solving the inverse problem

Full operator ( T ) and tensor product approximation (TKK)

| refinements | 0 | 1 | 2 | 3 | 4 | 5 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| time(T) in sec | 1.24 | 13.91 | 320.73 | - | - | - |
| time(TKK) in sec | 1.22 | 10.07 | 65.02 | 382.76 | - | - |

Reduced order model

| ref | 0 | 1 | 2 | 3 | 4 | 5 |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- |
| data compression | 0.001 | 0.005 | 0.028 | 0.114 | 0.457 | 1.831 |
| regularized normal equations | 0.002 | 0.001 | 0.002 | 0.003 | 0.003 | 0.003 |
| synthesis | 0.001 | 0.001 | 0.004 | 0.015 | 0.061 | 0.107 |
| reconstruction error | 0.112 | 0.108 | 0.107 | 0.107 | 0.107 | 0.107 |

Fluorescence diffuse optical tomography
Model
Inverse problem
Outline of model reduction approach

Abstract Analysis: Model reduction for $\mathcal{T} c=\mathcal{V}^{\prime} \mathcal{D}(c) \mathcal{U}$
Properties of the forward operator
Step 1: Tensor product approximation
Step 2: Quasi-optimal compression

## Model reduction in action: Application to FDOT

Truth approximation and implementation
Complexity estimates
Runtimes and ranks

## Conclusion

## Conclusion and final remarks

- Derived a systematic way to obtain a certified reduced order model of quasi-optimal rank for linear operators of the form $\mathcal{T} c=\mathcal{V}^{\prime} \mathcal{D}(c) \mathcal{U}$
- Advantages:
- Fast setup time (cost = one single evaluation of forward operator)
- Partial compression during recording (access to full data is never required)
- Problems with a similar structure $\mathcal{T}=\mathcal{V}^{\prime} \mathcal{D}(\cdot) \mathcal{U}$ :
- Inverse scattering [Colton \& Kress, Grinberg \& Kirsch, Somersalo et al 1992]
- Aeroacoustic source problems [Hohage et al 2020]
- Compression of $\mathcal{U}$ and $\mathcal{V}$ is related to
- optimal sources and detectors [Herrmann et al 2009, Krebs et al 2009, van den Doel 2012, Roosta-Khorasani et al 2014]
- optimal experimental design [Pukelsheim 2006]

[^2]
[^0]:    Compare to: [Markel et al: Fast linear inversion for highly overdetermined inverse scattering problems, Inverse Problems, 35 (2019)]

[^1]:    cf. [Dung et al: Hyperbolic cross approximation, Birkhäuser/Springer, Cham, 2018.]

[^2]:    [J. Dölz, H. Egger, M. Schlottbom: A model reduction approach for inverse problems with operator valued data https://arxiv.org/abs/2004.11827)]

